## **Exercises for Week 7**

1. Consider the following discrete-time frequency responses:

$$H_1(e^{j\omega}) = \frac{1}{1 - 0.1e^{-j\omega}}$$
$$H_2(e^{j\omega}) = \frac{1}{1 - 0.1e^{-j\omega}}$$

and

$$1 - 10e^{-j\omega}$$

Discuss the causality of the systems which correspond to the two spectra.

2. Consider a causal linear time-invariant system with system function

$$H(z) = \frac{1 - a^{-1}z^{-1}}{1 - az^{-1}}, \quad a \text{ is real}$$

- (a) Write the difference equation that relates the input x[n] and output y[n] of this system.
- (b) For what range of values of *a* is the system stable?
- (c) Find the impulse response of the system.
- (d) Is the system a finite impulse response (FIR) or infinite impulse response (IIR) filter?
- (e) Assume |a| < 1. Show that the system is an all-pass system, i.e., the magnitude of the frequency response is a constant. Also, specify the value of this constant.
- 3. Consider a discrete-time signal x[n] is passed through a system with transfer function H(z) to produce an output y[n].

Given y[n], is it possible to get back x[n]?

This is referred to as an equalization or deconvolution problem which arises in many applications such as communications. For example, the transmitter sends out information x[n]. After passing through the transmission channel (telephone line, air, etc.), the receiver obtains y[n] which is a filtered version of x[n].

(Hint: consider a simple case of  $H(z) = 1 - az^{-1}$ )

# **Solution**

## **Question 1**

plt.show()

Since  $H_1(e^{j\omega})$  and  $H_2(e^{j\omega})$  exist, it is clear that they are **stable** and their ROCs should include the unit circle.

That is, the ROC of  $H_1(e^{j\omega})$  is |z| > 0.1 which corresponds to a causal system. While the ROC of  $H_2(e^{j\omega})$  is |z| < 0.1 which corresponds to a noncausal system.

Plot the spectra of  $H_1(e^{j\omega})$  using Python:

```
from scipy.signal import freqz
import numpy as np
b = np.array([1])
a = np.array([1, -0.1])
w, h = freqz(b, a)
import matplotlib.pyplot as plt
fig, ax1 = plt.subplots()
ax1.set_title('Frequency Response H1')
ax1.plot(w, 20 * np.log10(abs(h)), 'b')
ax1.set ylabel('Amplitude [dB]', color='b')
ax1.set xlabel('Frequency [rad/sample]')
ax2 = ax1.twinx()
angles = np.unwrap(np.angle(h))
ax2.plot(w, angles, 'g')
ax2.set_ylabel('Angle (radians)', color='g')
ax2.grid()
ax2.axis('tight')
```



Plot the spectra of  $H_2(e^{j\omega})$  using Python:



Since  $H_1(e^{j\omega})$  is stable, the corresponding impulse response should be

$$H_1(e^{j\omega}) = \frac{1}{1 - 0.1e^{-j\omega}} \leftrightarrow h_1[n] = (0.1)^n u[n]$$

which implies that the system is causal as well.

### **Question 2**

2(a) Cross multiplying and taking the inverse z-transform, we get:

$$y[n] - ay[n-1] = x[n] - \frac{1}{a}x[n-1]$$

2(b) Since H(z) is causal and  $H(z) = \frac{1-a^{-1}z^{-1}}{1-az^{-1}} = \frac{z-a^{-1}}{z-a}$  with a single pole at z = a, then the ROC of H(z) should be |z| > |a|.

For stability, the ROC must include the unit circle, which implies |a| < 1 such that the pole z = a is located inside the unit circle.

2(c)

$$H(z) = \frac{1}{1 - az^{-1}} - \frac{a^{-1}z^{-1}}{1 - az^{-1}}, \qquad |z| > |a|$$
$$\implies h[n] = (a)^n u[n] - \frac{1}{a}(a)^{n-1} u[n-1]$$

2(d) The system is an IIR filter

2(e) If |a| < 1, the DTFT converges, we have

$$H(e^{j\omega}) = H(z)|_{z=e^{j\omega}} = \frac{1 - a^{-1}e^{-j\omega}}{1 - ae^{-j\omega}}$$
$$\left|H(e^{j\omega})\right|^{2} = H(e^{j\omega}) \cdot H^{*}(e^{j\omega}) = \frac{1 - a^{-1}e^{-j\omega}}{1 - ae^{-j\omega}} \cdot \frac{1 - a^{-1}e^{j\omega}}{1 - ae^{j\omega}}$$
$$\left|H(e^{j\omega})\right| = \left(\frac{1 + \frac{1}{a^{2}} - \frac{2}{a}\cos\omega}{1 + a^{2} - 2a\cos\omega}\right)^{\frac{1}{2}} = \frac{1}{|a|} \left(\frac{a^{2} + 1 - 2a\cos\omega}{1 + a^{2} - 2a\cos\omega}\right)^{\frac{1}{2}} = \frac{1}{|a|}$$

As a result, the magnitude frequency response is a constant of  $\frac{1}{|a|}$ .

#### **Question 3**

Consider  $H(z) = 1 - az^{-1}$  which is causal and stable:

$$Y(z) = H(z) \cdot X(z) = X(z) - az^{-1}X(z) \Longrightarrow y[n] = x[n] - ax[n-1]$$

To get back x[n] from y[n], we need to pass y[n] through the following system:

$$G(z) = \frac{1}{1 - az^{-1}}$$
$$R(z) = G(z) \cdot Y(z) = \frac{1}{1 - az^{-1}}Y(z)$$
$$\Rightarrow R(z)(1 - az^{-1}) = Y(z) \Rightarrow r[n] = ar[n - 1] + y[n]$$

In practical implementation, the inverse system should be causal and stable. That is, the impulse response is  $g[n] = a^n u[n]$  which requires |a| < 1.

This also means that the zero of (i.e., the pole of 1/H(z)) should be inside the unit circle.

For the general case:

$$H(z) = \frac{B(z)}{A(z)}$$

where A(z) and B(z) are polynomials in  $z^{-1}$ .

For a feasible H(z), it should be stable and thus all its poles should be inside the unit circle.

For a feasible inverse system, i.e., 1/H(z), it should be stable and thus all its poles should be inside the unit circle, which means all the zeros of H(z) should be inside the unit circle. The system is referred to as minimum phase system.

#### Demonstration via Python example:



Filter this sequence by casual  $H(z) = 1 + 2z^{-1}$  and stable output is observed



Reconstruct the sequence by filtering y[n] with  $\frac{1}{H(z)} = \frac{1}{1+2z^{-1}}$  and unstable inverse is observed.



Filter this sequence by casual  $H(z) = 1 + 0.5z^{-1}$  and stable output is obtained



Reconstruct the sequence by filtering y[n] with  $\frac{1}{H(z)} = \frac{1}{1+0.5z^{-1}}$  and stable inverse x[n] is observed.

r = signal.filtfilt(np.array([1]), np.array([1, 0.5]), y)

plt.stem(n,r);
plt.title('Reconstructed Sequence
by 1/H(z) = 1/(1-0.5z^-1)')
plt.xlabel('n')
plt.ylabel('Amplitude')
plt.show()

