Human

- Human Models
- Human Senses
- Human Memory and Reasoning
- Mental Model

Why Study Human?

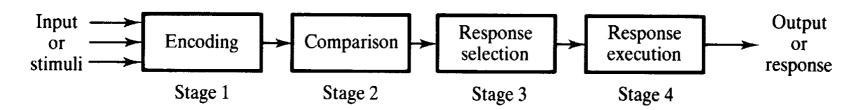
We are the users

When we try to understand something, particularly new, we use a combination of

- What our senses (sight, hearing, touch, smell, taste) are telling
- Past experience
- Our expectations
- e.g., When we browse a new Web, our past experience tells us that underlined blue text is supposed to be a link
- e.g., When we are given a new product with buttons, we expect that it is operated by pressing the buttons

Human Model

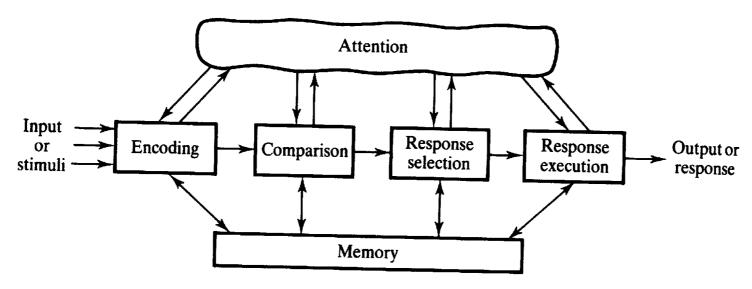
Modelled as information processing system



- Stage 1: encode information (sight, hearing, touch, smell, taste) from environment into internal representation
- Stage 2: internal representation of the stimuli is compared with the memorized representations in brain
- Stage 3 is concerned with deciding on a response to encoded stimulus
- Stage 4 deals with organization of response & necessary action

Human Model

Extending the human information processing model



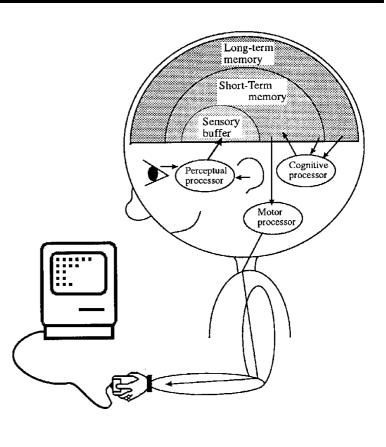
Attention

- Selective attention ability to attend to certain events from a number of competing stimuli (cocktail party phenomenon)
- Divided attention ability to carry more than one task simultaneously (driving and holding a conversation)

Human Model

Card, Moran & Newell's Model:

- Comprise 3 interacting systems:
 - Perceptual system consists of sensors & associated buffer memories:
 - Visual image store
 - Auditory image store
 - Cognitive system consists of short-term & long-term memories
 - Motor system carries out response formulated by cognitive system



Human Senses

The five senses are:

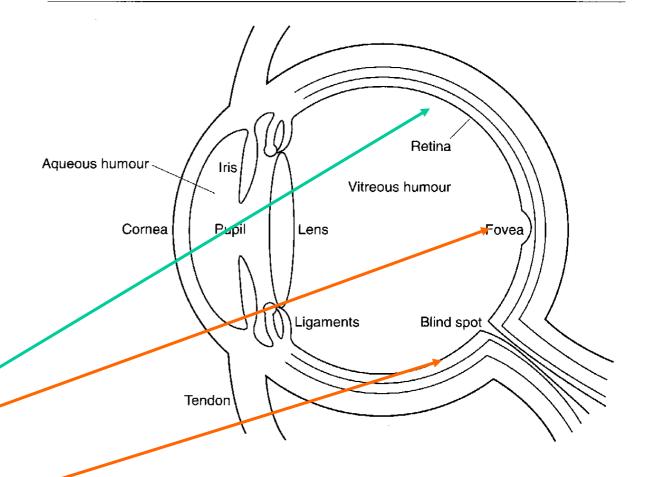
- Sight
- Hearing
- Touch
- Smell
- Taste

They can interact with computing systems:

Input to Human	Output from Human Speech	
Vision		
Audition	Motor Control	
Balance	Biometrics, e.g., fingerprint	
Olfaction		
Touch		
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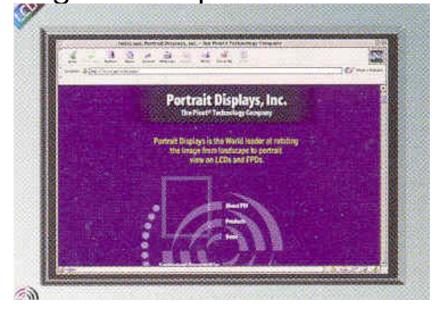
Eye

- Mechanism for receiving light & transforming it into electrical energy
- Light reflects from objects; their images are focused upside down on retina
- Retina contains
 - Fovea: colour vision, pattern detection
 - Outer part: sensitive to light, movement detection



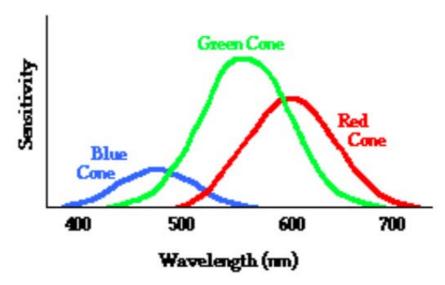
Design implication:

 A user concentrating on the middle of the screen cannot be expected to read text on the bottom line because outer part is not good for pattern detection



⇒ If we want a user to see an error message at the bottom of the screen, since the outer part is capable for change detection, the message should be flashing

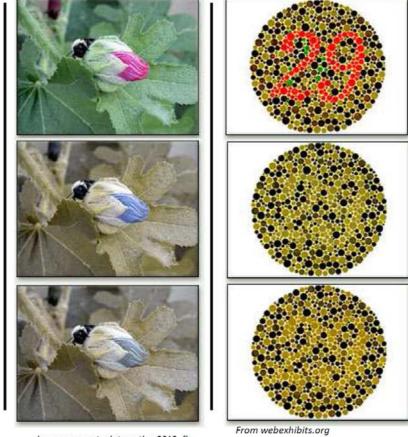
- The cones are the color-sensing cells of the retina
- There are three kinds of cones, each sensitive to its own range of wavelengths within the visible light spectrum, which are referred to as red cones, green cones, and blue cones
- Eyes are most sensitive to green but least sensitive to blue



- Defective colour vision is not uncommon:
 - 8% males, 0.5% females
 - Red-Green colour blindness is most common
 - Normal

- Protans
 - (red weak)

- Deutans
 - (green weak)



human computer interaction 2013, fiv

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A theory about vision is constructivism:

- Our brains do not create pixel-by-pixel images
- Our minds create, or construct, models that summarize what comes from our senses
- These models are what we perceive
- When we see something, we do not remember all the details, only those that have meaning for us

Design implication:

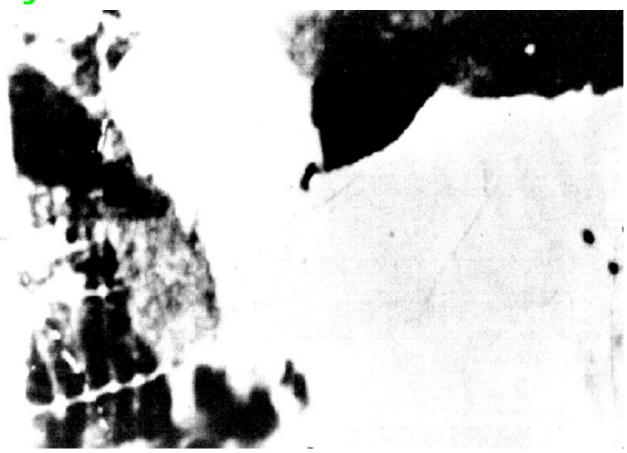
 Do not expect people "see" all the details of an interface because people filter out irrelevant information and save only the important ones

How many items are there on top menu bar of https://www.cityu.edu.hk/?

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Constructivist theory states that context plays a major role in what we see in an image

What do you see?

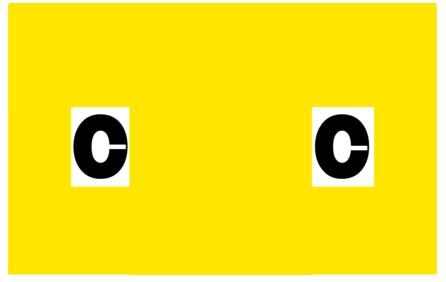


Why we cannot see it at first?

- The image is too blurry
- We had no idea what to expect because there was no context

Now we have context, we can recognize easily next time

Are these letters the same?

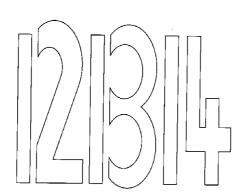


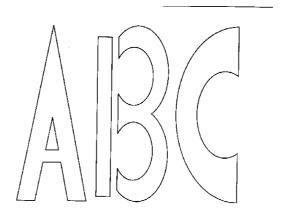
With context, the answer will be different:

top ace

Design implication:

Context can help in resolving ambiguity





HEAD or HERO? INITIATING TECHNOLOGY ADVANCEMENTS In line with the role statement of CityU, the Department emphasizes applied research and applicationoriented teaching. After a few years of endeavour, I feel grateful to see that our aspiration to transfer research achievements to the society has been realized. Last year, we obtained one patent and submitted six patent applications. Moreover, seven licensing agreements with telecommunication, Internet and software companies were signed because of the high industrial relevance and marketability of our applied research. May I give thanks to our industrial partners, colleagues and the University for their support in the course of opening up the applied research frontier. Here, I am with great pleasure to introduce to you some of our applied research work in the areas of 3G mobile entertainment and communication, security and monitoring database management, computer graphics and pattern recognition. All of them are ready for commercialization or technology transfer in form of consultancy, contract research or licensing. While we are extending our arm to the industry, we believe that we should also interact with the general public and bring our innovative and practical work to their knowledge. To this end, we have been organizing different activities like exhibitions, road shows and seminars to share our work with the public. Apart from developing applied research, we are also devoted to education and particularly, its synergy with our applied research strengths. Our programmes stress hands-on experience and the independent ability to master and even pioneer the state-of-the-art technology. Coupled with solid theoretical foundation, our application-oriented education stimulates students' learning and creativity. Inside this newsletter, you can find some of our students' innovative work on the prevailing mobile technology. Soon, we will revamp our undergraduate programme to better equip students with professionalism and readily applicable technical skills in response to the needs of the society. I hope you enjoy the reading, and look forward to your continuous support and advice

Another concept from constructivism: images are partitioned into

- Figure (i.e., foreground)
- Ground (i.e., background)

Sometimes figure and ground are ambiguous

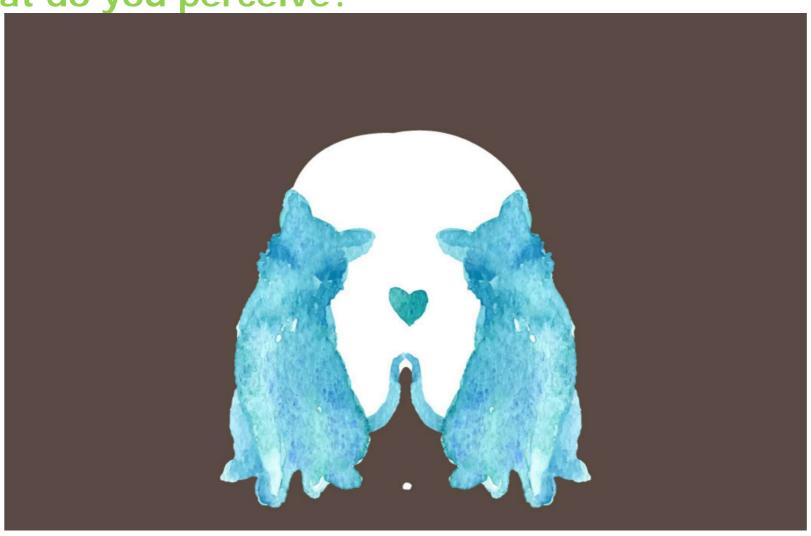
Example:

A person who sells flowerpots may see a vase while a person who likes observing people's faces may see two faces



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What do you perceive?



- Main idea: We do not see things in isolation, but as parts of a whole
- We organize things into meaningful units using
 - Proximity: we group by distance or location
 - Similarity: we group by type
 - Symmetry: we group by meaning
 - Continuity: we group by flow of lines (alignment)
 - Closure: we perceive shapes that are not (completely) there

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Principle of proximity

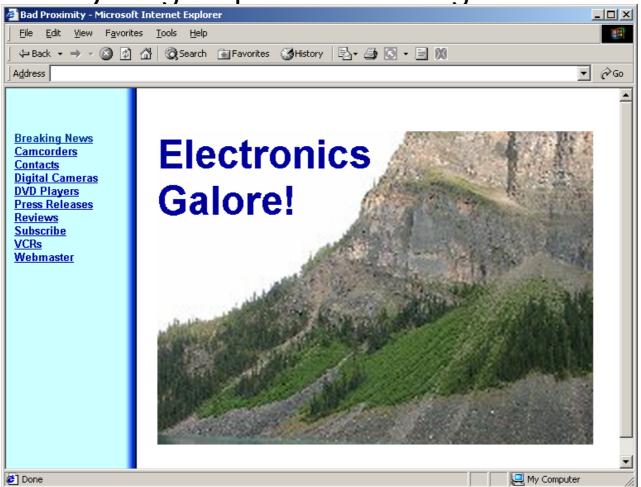
Example:



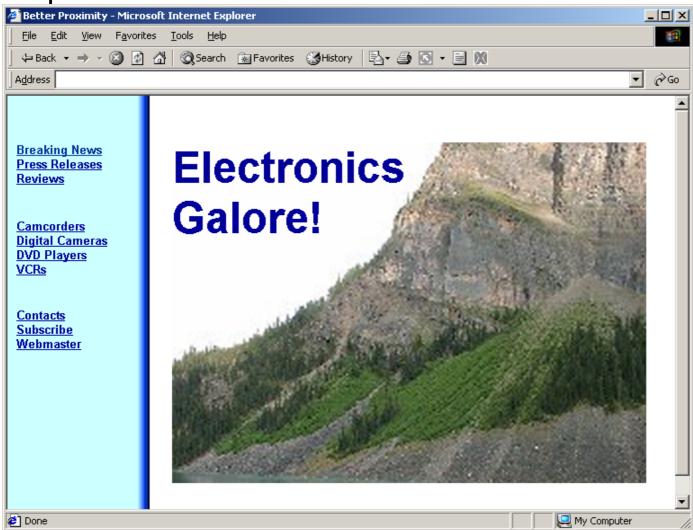
We tend to perceive any closely clustered objects as a group

Design implication:

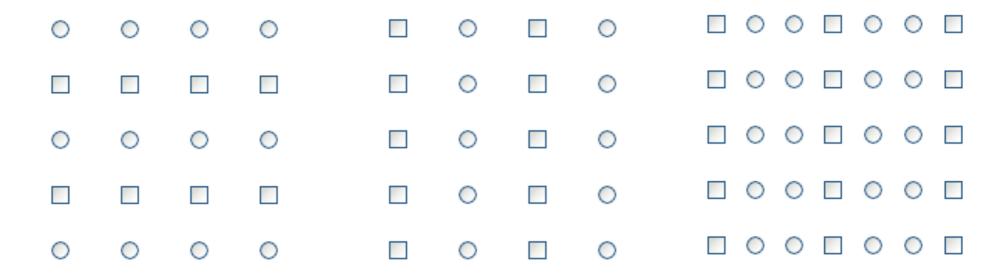
Use proximity to group related things



Improved version:



Principle of similarity: Objects that have similar visual characteristics, such as size, shape or colour will be seen as a group



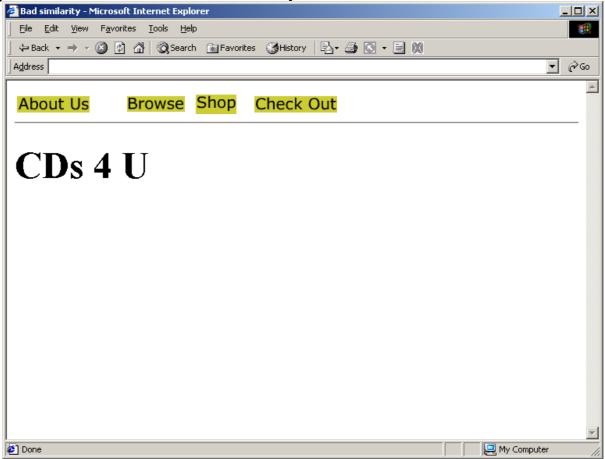
Rows of similar objects

Columns of similar objects

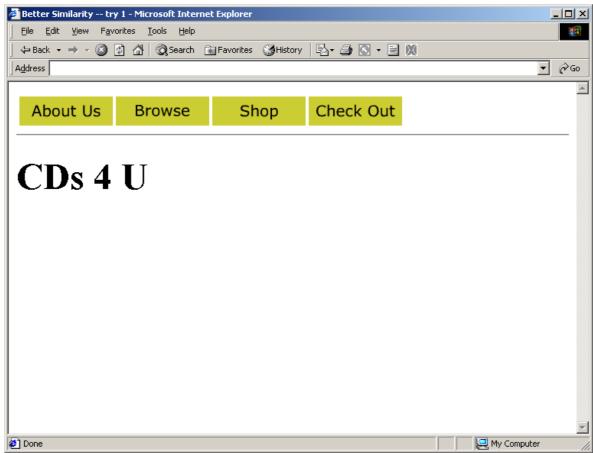
Grouped columns

Design implication:

Use similarity to make menu options the same size:



Improved version:



Apart from size, other similarity hints include shape, texture, boldness, etc.

Principle of symmetry: we use our experience and expectations to make groups of things

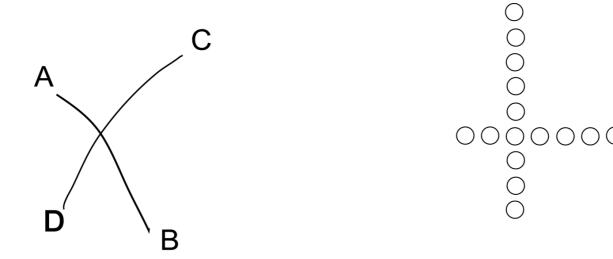




We see two triangles

We see three groups of paired square brackets

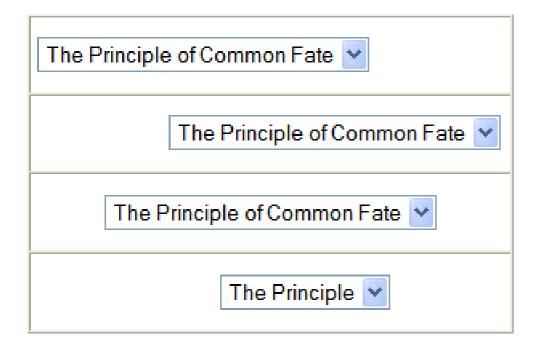
Principle of continuity: we group by flow of lines, that is, we tend to see things as smooth, continuous representations rather than abrupt changes

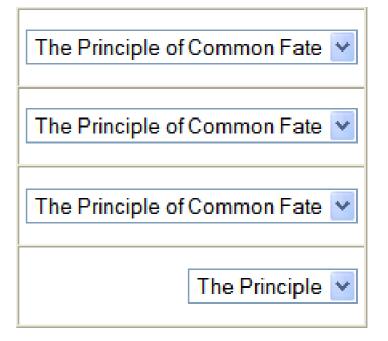


We see curves AB and CD, not AC and DB, and not AD and BC

We see two rows of circles, not two L-shaped groups

Which is better? (a) or (b)?

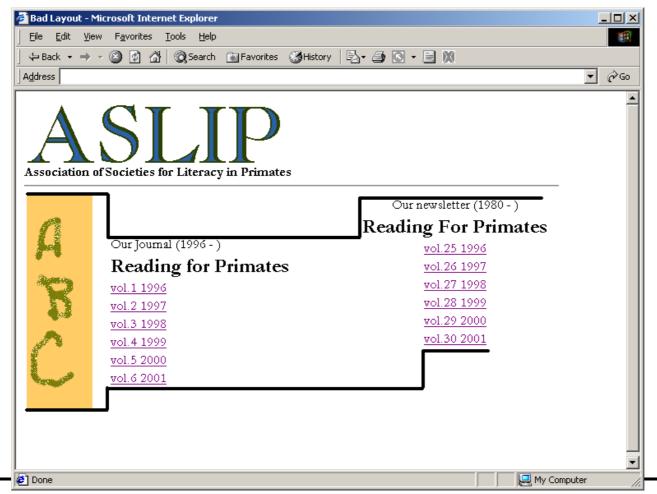




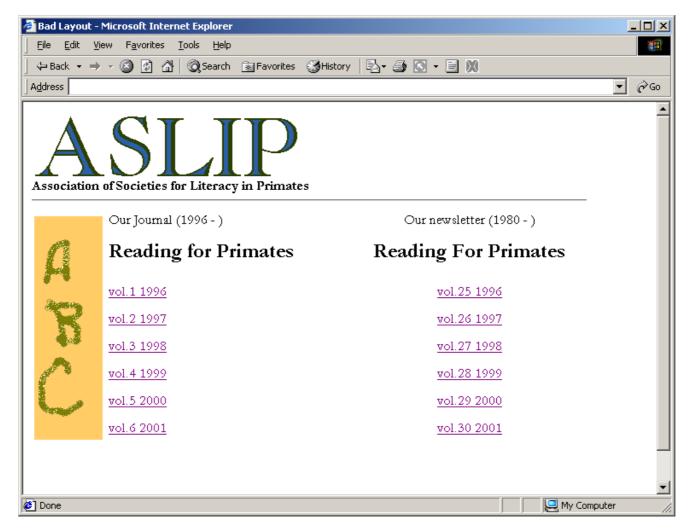
(a) (b)

Design implication:

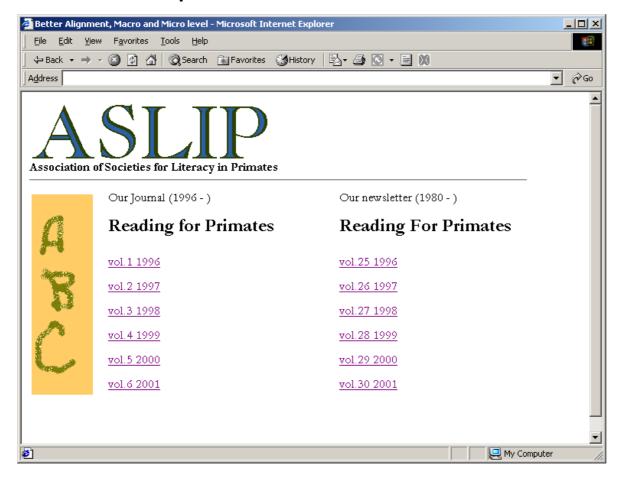
Use alignment to improve layout



An improved version:

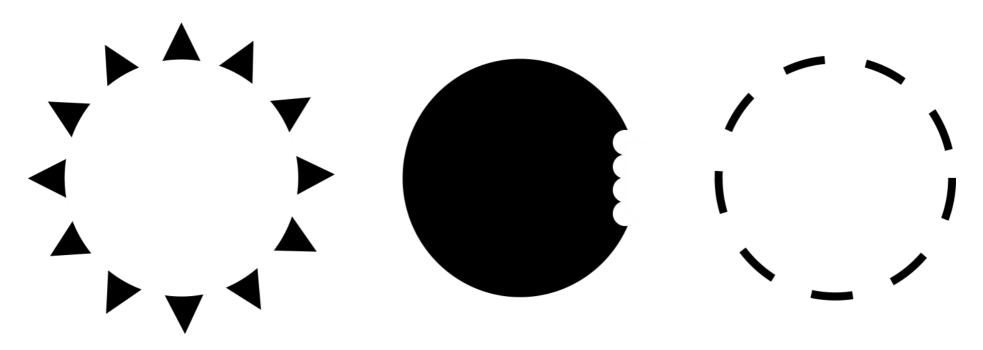


Can be further improved:



Principle of closure: we mentally "fill in the blanks"

Examples:



All are seen as circles although they are not exactly

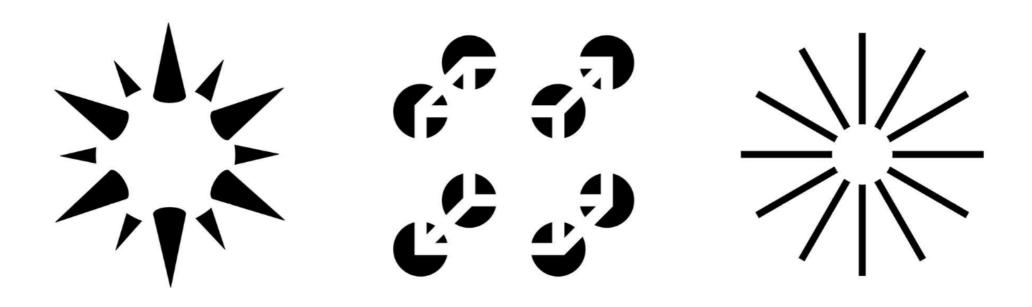




Any Gestalt's principles have been applied in the above two figures?

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How about these?





Any Gestalt's principles have been applied?

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Reading Speed/Accuracy

Speed of reading:

Word shape is important to recognition

Which one is easier to recognize?

INTRODUCTION

Introduction

This was an advertisement appeared several times in Ming Pao, 2001

Any problem?



Reading Speed/Accuracy



Intended Action No 137/2019

HCA

/2019

IN THE HIGH COURT OF THE
HONG KONG SPECIAL ADMINISTRATIVE REGION
COURT OF FIRST INSTANCE
ACTION NO OF 2019

BETWEEN

MTR CORPORATION LIMITED

Plaintiff

MTR obtained interim injunction from High Court

Any problem? Any design implication?

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Reading Speed/Accuracy

This was an advertisement appeared in Hong Kong Economic Times, Sep. 2019

Proofread is important even for lower-case words!

An Open Letter to HKUST Students

Dear HKUST students

We are a group of alumni graduated from HKUST. We hope this letter finds you well.

Autumn comes and the school year restarts soon. It brings us back to the days that we still lived on campus - working hard in the library and enjoying our lives in the ivory tower. However, a lot of things seem to have been changed.

We are writing to express our deep concerns about the incoming strike on campus. We would like to ask you to think twice before participating.

Just like you, we love freedom. However, we know that freedom does not mean you can do whatever you want to do, instead, freedom means you can refuse to do whatever you don't agree with. There are faculties and students who do not want to participate in the strike. Please bear in mind that their freedom does not value less than those who go on strike.

Just like you, we pursue democracy. However, we know that there is a bottom line of democracy. We are all Hong Kongers, and we are also Chinese. Do not be misled by Seperatism. Please remember that one's home can be called a home only when the national sovereignty and territorial integrity is safeguarded.

Just like you, we cherish the rule of law. So we cannot agree that violent criminals we have seen recently on news should be granted pardons, no matter what intensions they had. No one should be above the law.

Just like you, we support freedom of speech. That is to say, even though I disapprove of what you say, I will defend to the death your right to say it. However, violence is never a solution but a troublemaker. We thank President Wei Shyy for hosting president forums to encourage open discussion. Let's have politics stay in politics, academics remain with academics.

We also know that there are injustices and inequalities all around the world. We'd like to share a quote from former US President John F. Kennedy, "Ask not what your country can do for you, ask what you can do for your country."

Located in the east of Hong Kong, our beautiful campus is the best place for you to enjoy the splendid sunrise. We hope you remain possitive and optimistic. We strongly believe that tomorrow will be better in Hong Kong.

Best regards, A group of HKUST alumni

Reading Speed/Accuracy

- For font size, 9 to 12 points are good and similar
- For text width, 2.3 and 5.2 inches are good and similar

$$\begin{split} \sigma_x^2 &\triangleq E\{(\hat{x} - x)^2\} = c^2 E\{(\hat{\tau} \cos(\hat{\phi}) - \tau \cos(\phi))^2\} \\ &\approx c^2 E\{(\epsilon_{\tau} \cos(\hat{\phi}) - \tau \sin(\phi) \sin(\epsilon_{\phi}))^2\} \end{split}$$

 $\approx c^2(\sigma_\tau^2 \cos^2(\phi) + \tau^2 \sigma_\phi^2 \sin^2(\phi))$ In a similar manner, the variance of \hat{y} is derived as

$$\sigma_y^2 \stackrel{\triangle}{=} E\{(\hat{y} - y)^2\}$$

 $\approx c^2(\sigma_\tau^2 \sin^2(\phi) + \tau^2 \sigma_\phi^2 \cos^2(\phi))$

As a result, the variance of the range error, denoted by ω^2 is

$$\sigma_r^2 \stackrel{\triangle}{=} E\{(\hat{x} - x)^2\} + E\{(\hat{y} - y)^2\} \approx c^2(\sigma_r^2 + \tau^2\sigma_\phi^2)$$

which is a function of τ , σ_{τ}^2 and σ_{ϕ}^2 .

The CRLB gives a lower bound on variance attainable by any unbiased estimators and thus it can be served as a benchmark to contrast with the mean square error of the positioning algorithm. The CRLBs for x and u are computed from [7]

$$CRLB(\theta_i) = [I^{-1}(\theta)]_{i,i}, i = 1, 2$$
 (6)

where

$$[I(\theta)]_{i,j} = -E\left\{ \frac{\partial^2 \ln p(\mathbf{z}|\theta)}{\partial \theta_i \partial \theta_j} \right\},$$

 $i = 1, 2$ and $j = 1, 2$

and $\mathbf{z}|\boldsymbol{\theta}\rangle = \frac{1}{\sqrt{2\pi\sigma_{\pi}^2}}$

$$\cdot \exp\left(-\frac{1}{2\sigma_r^2}\left(\hat{\tau} - \frac{\sqrt{16-4\sigma_s^2}}{c}\right)\right)$$

$$-\frac{1}{\sqrt{2\pi\sigma_s^2}}\exp\left(-\frac{1}{2\sigma_\theta^2}\left(\hat{\phi} - \tan^{-1}\left(\frac{y-y_s}{x-x_s}\right)\right)^2\right) (8)$$

is the probability density function (PDF) of $\nu=[\hat{\tau},\hat{\phi}]$ parameterized by the MS position, and $|I(\theta)|_{i,j}$ represents the (i...)th clement of $I(\theta)$, which is known as the Fisher information matrix (FIM). The FIM is computed as

$$I(\theta) = \frac{1}{r^2} \begin{bmatrix} \frac{\cos^2(\phi)}{r^2} + \frac{\sin^2(\phi)}{r^2\sigma_\phi^2} & \frac{\sin(2\phi)}{2} \left(\frac{1}{\sigma_\tau^2} - \frac{1}{r^2\sigma_\phi^2}\right) \\ \frac{\sin(2\phi)}{2} \left(\frac{1}{\sigma_\tau^2} - \frac{1}{r^2\sigma_\phi^2}\right) & \frac{\sin^2(\phi)}{\sigma_\tau^2} - \frac{\cos^2(\phi)}{r^2\sigma_\phi^2} \end{bmatrix}$$

Taking the inverse of $I(\theta)$ yields $[I^{-1}(\theta)]_{1,1} = c^2(\sigma_r^2\cos^2(\phi) + \tau^2\sigma_\phi^2\sin^2(\phi))$ and $[I^{-1}(\theta)]_{2,2} = c^2(\sigma_r^2\sin^2(\phi) + \tau^2\sigma_\phi^2\cos^2(\phi))$, which indeates the optimality of the ToA-AOA hybrid algorithm at sufficiently small noise conditions. As a result, the CRLB for the range is also given by $c^2(\sigma_r^2 + \tau^2\sigma_\phi^2)$. It is noteworthy that (2) is in fact the maximum likelihood estimate bocause (8) is maximum et al. $(2, \sigma_r^2 + \tau^2\sigma_\phi^2)$.

3. Simulation Results

Extensive computer simulations were conducted to evaluate the TOA-AOA hybrid mobile positioning algorithm using a single BS with multiple antennas in the LOS scenario. It was assumed that necessary changes to the mobile networks had been made [4] so that the measured TOA and AOA were of high accuracy, even in the presence of multipath propagation [8]. We considered a microcall with radius of 560 m and the measurement errors were uncorrelated zero-mean Caussian processes. The worst-case performance was investigated such that the MS was randomly located at the cell boundary with ϕ uniformly distributed over $[0,2\pi)$.

Figure 1 shows the standard deviation of the range of the for $\sigma_\tau \in [-80, -50]$ dBs at $\sigma_\delta = 0$ and $\sigma_\delta = 0.1 \text{rad}$. It can be seen that the estimation securacy of the hybrid estimator met the CRLBs for the range in both cases. Note that at $\sigma_\delta = 0.1 \text{ rad}$, the range deviation was approximately equal to 17 dBm or $\sigma_\tau \approx 50\,\mathrm{m}$, for $\sigma_\tau < -68$ dBs because the AOA error dominated. Another similar test to examine the location error versus σ_b at $\sigma_\tau = 0$ and $\sigma_\tau = 0.1\,\mu\text{s}$ was also performed and the results are shown in Fig. 2. Again, the range deviations agreed well with the CRLBs except that there was slight discrepancy for $\sigma_\phi > -3$ dBrad because (3) and (4) were derived based on small ϵ_b assumption. For

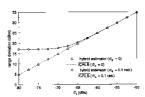


Fig. 1 Range standard deviation versus of

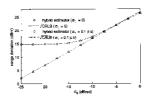


Fig. 2 Range standard deviation versus σ_d

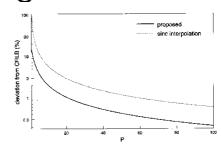


Fig. 1. Deviation from CRLB versus P for white signal.

limiting value $\lim_{l\to\infty}\sum_{j=-p}^{l}\operatorname{sinc}^2(j-D)=\pi^2/3$ even for a small P, and it can be shown that (10) is an unbiased estimator for white s(k), the mean square delay error (MSDE) of the proposed method will approach the CRLB for a wide range of filter lengths. On the other hand, the delay variance using sine interpolation is given by

$$\operatorname{var}(\hat{D}'') \approx \operatorname{CRLB} \frac{3 \sum_{j=-P}^{p} \operatorname{sinc}'^{2}(j-D)}{\pi^{2} (\sum_{j=-P}^{p} \operatorname{sinc}(j-D) \operatorname{sinc}''(j-D))^{2}},$$
 (16)

where it also attains the CRLB as $P \to \infty$ but has a convergence rate lower than (15). To illustrate this, Fig. 1 plots the deviation from the CRLB, that is, $(\text{var}(\vec{D}^2) - \text{CRLB})/\text{CRLB}$, for both schemes versus P at D = 0.7 s, and it can be observed that the percentage error of (15) is less than that of (16) for the whole range of P by approximately 3–6 times. It is noteworthy that since the sinc interpolator is biased for finite P, the resultant MSDE will be much larger than (16).

4. Numerical examples

Simulation tests were carried out to evaluate the performance of the proposed delay estimator using least-squares filter weights. Comparisons of MSDEs were also made with the sine interpolator and the CRLB. The searching procedures of (2) and (10) were performed by the bisection method. The source signal was Gaussian distributed with unity power and different SNRs were obtained by proper scaling of the random noise sequences. For simplicity, the additive noises were assigned to have identical power. The time difference D was set to 0.7 s, the data length N was 1000 and $\alpha = 1$ was selected. The MSDEs obtained were based on 1000 independent runs.

In the first test, the source signal was a white process. Fig. 2 shows the MSDEs of the proposed method and sine interpolator using P=3 and P=15, as well the CRLB, for SNR $\in \{-10,20|B$. It can be seen that when SNR $\geqslant -6$ dB, the proposed approach was superior to the sine interpolation method using P=3 and P=15, for the whole range of SNRs and for SNR $\geqslant 4$ dB, respectively. Furthermore, the proposed method with P=3 and P=15 had very similar performance and both met the CRLB for SNR $\geqslant -6$ dB, which indicated that the delay estimation performance of (10) was almost

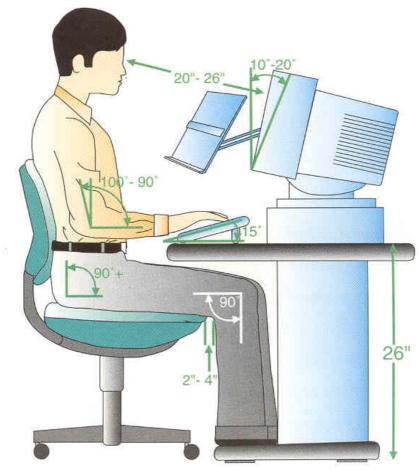
Hearing

- Human can hear frequencies from 20Hz to 15kHz
- Less accurate in distinguishing high frequencies than low frequencies
- Auditory system filters sounds can attend to sounds over background noise/interference. For example, we can talk with our friend in a very noisy Chinese restaurant (cocktail party phenomenon)
- A sound's loudness is measured in decibels (dB), and level between 20 dB and 70 dB constitutes comfortable
- Apart from hearing sound, our ears are capable to get the distances and directions of the sound sources
 Why position information can be obtained?

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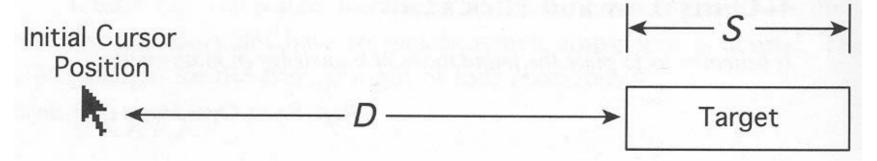
Touch

- Key sense for visually impaired persons
- Aspects include



- Time taken to respond to stimulus: reaction time + movement time
- Reaction time depend on stimulus type
 - Visual 200ms
 - Auditory 150ms
 - Pain 700ms
 - Combined signal will result in faster response
- Movement time dependent on age, fitness, etc.
- ↓ reaction time ↓ accuracy in unskilled operator but not in skilled operator

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Fitts' law describes the average time taken to hit a screen target:

$$T_M = a + b \log_2(D/S + 1)$$

where

- a & b are constants determined experimentally
- T_M is movement time (in ms)
- D is Distance
- S is Size
- ⇒ Targets in general should be large as possible & the distances as small as possible

Example:

- Suppose for a 15-inch flat panel display, the average distance the cursor between the menu bars is 80 mm
- Size of menu bar Macintosh: 50 mm & Windows: 5mm
- a=50, b=150

Calculated time to move the cursor to a menu item on Macintosh

$$T_M = 50 + 150 \log_2(80/50 + 1) = 256 \text{ ms}$$

For Windows,

$$T_M = 50 + 150 \log_2(80/5 + 1) = 663 \text{ ms}$$

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When there are multiplicity of choices, we need to choose the appropriate target prior to moving the cursor:



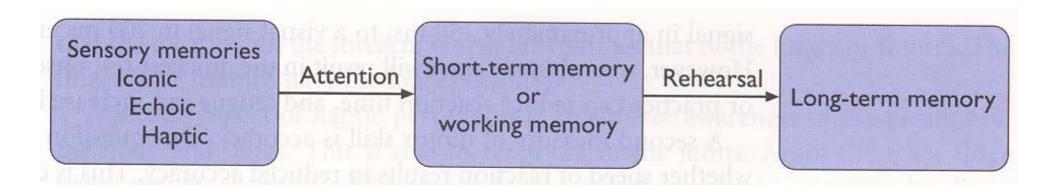
Required time to choose can be described by Hick's law:

$$T_C = a + b \log_2(N+1)$$

where N is number of options and the probabilities of taking each alternative are equal

3 types of memory model

- Sensory memory (vs I/O buffer)
 - Hold data received from external world
- Short-term or working memory (vs RAM)
 - Where information is processed
- Long-term memory (vs hard disk)
 - Hold information for long time, although not all information can be retrieved evenly



- Sensory memory acts as buffers for stimuli received via senses
- Constantly overwritten
- Information passes from sensory to short-term memory by attention (e.g., you are constantly seeing but you will not pay attention to all things you see)
- Attention or selection of stimuli is governed by level of interest or need

e.g., cocktail party phenomenon: we can attend to one conversation over background noise and other voices but we may choose to switch our attention to another conversation if we hear our name mentioned

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- Short-term memory (STM) is used for temporary recall of information
 - Rapid access 70ms
 - Rapid decay 200ms
 - Limited capacity 7 +/- 2 digits or chunks
- Long-term memory (LTM) is the main resource for all our knowledge
 - Slow access 100 ms
 - Slow decay, if any
 - Huge or unlimited capacity

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Memory capacity can be improved via:

- Chunking
- Let people recognize information rather than recall it How many chunks in the following?

85234427780

The chunks can be 852, 3, 4, 4, 2, 7, 7, 8, $0 \Rightarrow 9$ chunks How about this?

852 3442 7780

There are now 3 chunks: 852, 3442, 7780

However, sometimes we cannot do chunking, e.g., can you remember:

vsdfnjejn7dknsdnd33s

Design implication:

Facilitate users to do chunking, e.g., make your URL easy for chunking:

www.bestbookbuys.com

The chunks are:

WWW.

best

book

buys

.com

Another application is to use chunking in memorizing phone number, 3442, 7780

Recognition versus Recall:

Is my telephone number 3442 7780? What is my telephone number?

Which one does not belong to Norman's usability principles?

- A. Affordance
- **B.** Constraints
- C. Flexibility
- D. Feedback
- E. None of the above

State Norman's usability principles.

- Multiple choice: you can recognize the answer
- Essay: you must recall the answer

Design implication:

 Design systems that rely on people's ability to recognize information rather than forcing them to recall it, in order to reduce user's memory burden

e.g., a computer with a GUI allows us to recognize commands on a menu, instead of remembering them as in DOS and UNIX

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- Three forms of reasoning:
- 1. Deductive reasoning
 - Derive logically necessary conclusion from given premises
 - e.g., If it is Friday then she will go to work ⇒It is Friday. Therefore she will go to work
 - Logical conclusion not necessarily true:
 - e.g., If it is raining then the ground is dry
 - \Rightarrow It is raining. Therefore the ground is dry
 - ⇒ It is valid deduction but not true
 - Human deduction poor when truth & validity clash

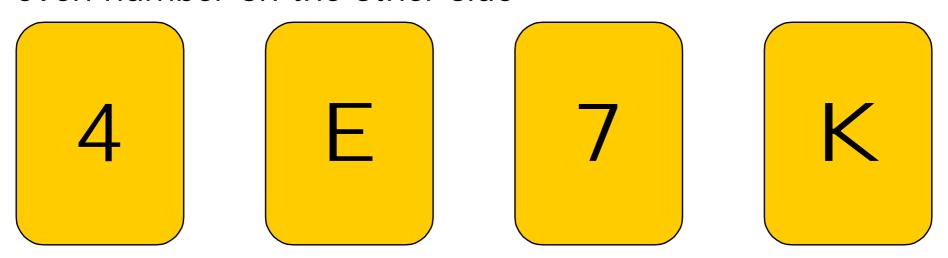
2. Inductive reasoning

- Generalise from cases seen to cases unseen
 e.g., All elephants we have seen have trunks
 therefore all elephants have trunks.
- Unreliable: can only prove false not true.
- However, humans are not good at using negative evidence e.g., Wason's cards

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Wason's cards: each card has a number on one side and a letter on the other

Statement "if a card has a vowel on one side it has an even number on the other side"



Which card(s) would you need to pick up to check this statement?

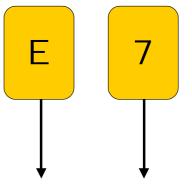
Most people: E & 4

In fact, we need to check E & 7

4

Because "If A, then B."

⇔ "If NOT B then NOT A."



- (a) E (to check if A then B)
- (b) 7 (to check if NOT B then NOT A)
- (c) 4 (to check if B then what)
- (d) K (to check if NOT A then what)
- (c) & (d) are no use for checking the statement.

How about if the condition "each card has a number on one side and a letter on the other" is not stated? Which card(s) would you need to pick up to check the statement?

Design implication:

Avoid negative evidence, e.g., If not Exit, don't press "X"

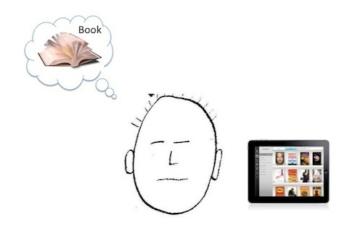
- 3. Abductive reasoning
 - Reasoning from event to cause
 e.g., Sam drives fast when drunk
 If you see Sam driving fast, assume he is drunk
 - Unreliable: can lead to false explanations.
 e.g., Sam may need to do an emergency matter

- Don Norman's definition: "the model people have of themselves, others, the environment, & the things with which they interact. People form mental models through experience, training & instruction"
- An internal representation of a user's current conceptualization and understanding of a system
- The more people learn about a system and how it functions, the more their mental models develop, e.g., a TV engineer has a deep mental model of how TVs work that allows them to work out how to set them up and fix them, while an average citizen only has a good mental model of how to operate a TV but a shallow mental model of how it works

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- Knowledge developed in learning & using a system How to use it? How it works?
 - e.g., Make a phone call:
 - Pick up the phone
 - Dial the number I want to call
 - Hear the phone on the other end ringing
 - The person at the other end answers
 - e.g., Waiting for an elevator:
 - Press the button
 - To reduce the waiting time, we need to press the button more than once?

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e.g., iPad for book reading

Imagine that you have never seen an iPad, but I have just handed one to you and told you that you can read books on it. Before you turn on the iPad, before you use it, you have a model in your head of what reading a book on the iPad will be like. You have assumptions about what the book will look like on the screen, what things you will be able to do, and how you will do them - things like turning a page, or using a bookmark

If you have used an iPad before, your mental model of reading a book on an iPad will be different than that of someone who has never used one, or does not even know what iPads are

If you have been using a Kindle user, then your mental model will be different from someone who has never read a book electronically. And once you get the iPad and read a couple of books on it, whichever mental model you had in your head before will start to change and adjust to reflect your experience

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- Mental models are:
 - Unscientific—They are often based on guesswork and approximations
 - Partial—They do not necessarily describe whole systems, just the aspects that are relevant to the persons who formulate them
 - Unstable—They are not concrete formulations, but evolve and adapt to the context
 - Inconsistent—They do not necessarily form a cohesive whole; some parts may be incompatible with other parts of the same model
 - Personal—They are specific to each individual and are not universal concepts that can be applied generally

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- Help to predict the operation of an unknown/unfamilar system
 - e.g., in an unfamiliar flat, we guess the light should be turned on using the nearest switch
- Users always have mental models & always develop & modify them, regardless of the particular design of a system
- By studying how people create mental models of interactive systems and by designing interactive systems that help the user create a more accurate mental model of the system, usability will improve
- Successful interface is built when
 Designer's conceptual model agrees with user's mental model

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